


PALM INTRANET

Day : Monday
Date: 7/17/2006
Time: 12:27:59

Inventor Name Search Result

Your Search was:

Last Name = SALISBURY

First Name = J.

Application#	Patent#	Status	Date Filed	Title	Inventor Name
60116891	Not Issued	159	01/22/1999	DYNAMIC ASSOCIATION OF MASTER AND SLAVE IN A MINIMALLY INVASIVE TELESURGICAL SYSTEM	SALISBURY JR., J. KENNETH
08429266	5587937	150	04/25/1995	FORCE REFLECTING HAPTIC INTERFACE	SALISBURY, J. K.
09508871	6786896	150	07/17/2000	ROBOTIC APPARATUS	SALISBURY, J. KENNETH
09964171	6587750	150	09/25/2001	REMOVABLE INFINITE ROLL MASTER GRIP HANDLE AND TOUCH SENSOR FOR ROBOTIC SURGERY	SALISBURY, J. KENNETH
09972322	6837883	150	10/05/2001	ARM CART FOR TELEROBOTIC SURGICAL SYSTEM	SALISBURY, J. KENNETH
10016661	Not Issued	71	10/29/2001	Long elements method for simulation of deformable objects	SALISBURY, J. KENNETH
10022114	6853965	150	11/16/2001	FORCE REFLECTING HAPTIC INTERFACE	SALISBURY, J. KENNETH
10052204	Not Issued	95	01/15/2002	REPOSITIONING AND REORIENTATION OF MASTER/SLAVE RELATIONSHIP IN MINIMALLY INVASIVE TELESURGERY	SALISBURY, J. KENNETH
10055565	Not Issued	71	10/26/2001	Method and apparatus for determining forces to be applied to a user through a haptic interface	SALISBURY, J. KENNETH
10076812	6991627	150	02/15/2002	ARTICULATED SURGICAL INSTRUMENT FOR PERFORMING MINIMALLY INVASIVE SURGERY WITH ENHANCED DEXTERITY AND SENSITIVITY	SALISBURY, J. KENNETH
10121283	6684129	150	04/11/2002	MASTER HAVING REDUNDANT DEGREES OF FREEDOM	SALISBURY, J. KENNETH
10314001	Not	93	12/05/2002	DEVICES AND METHODS FOR	SALISBURY, J.

	Issued			PRESENTING AND REGULATING AUXILIARY INFORMATION ON AN IMAGE DISPLAY OF A TELESURGICAL SYSTEM TO ASSIST AN OPERATOR IN PERFORMING A SURGICAL PROCEDURE	KENNETH
<u>10424536</u>	Not Issued	40	04/24/2003	Cooperative minimally invasive telesurgical system	SALISBURY, J. KENNETH
<u>10893613</u>	Not Issued	30	07/15/2004	Robotic apparatus	SALISBURY, J. KENNETH
<u>10990226</u>	Not Issued	41	11/16/2004	Force reflecting haptic interface	SALISBURY, J. KENNETH
<u>11019808</u>	Not Issued	20	12/20/2004	Robotic hand with extendable palm	SALISBURY, J. KENNETH
<u>11319012</u>	Not Issued	20	12/27/2005	Multi-user medical robotic system for collaboration or training in minimally invasive surgical procedures	SALISBURY, J. KENNETH
<u>11377225</u>	Not Issued	20	03/15/2006	Repositioning and reorientation of master/slave relationship in minimally invasive telesurgery	SALISBURY, J. KENNETH
<u>06364774</u>	Not Issued	166	04/02/1982	MULTI-FINGERED ROBOTIC HAND	SALISBURY, J. KENNETH
<u>06680605</u>	<u>4921293</u>	150	12/12/1984	MULTI-FINGERED ROBOTIC HAND	SALISBURY, J. KENNETH
<u>07184273</u>	<u>4903536</u>	150	04/21/1988	COMPACT CABLE TRANSMISSION WITH CABLE DIFFERENTIAL	SALISBURY, J. KENNETH
<u>07438524</u>	<u>5046375</u>	150	11/17/1989	COMPACT CABLE TRANSMISSION WITH CABLE DIFFERENTIAL	SALISBURY, J. KENNETH
<u>07682588</u>	<u>5207114</u>	150	04/08/1991	COMPACT CABLE TRANSMISSION WITH CABLE DIFFERENTIAL	SALISBURY, J. KENNETH
<u>07861369</u>	Not Issued	166	03/31/1992	SYSTEM AND METHOD FOR MEASURING JOINT MOVEMENT	SALISBURY, J. KENNETH
<u>07900663</u>	<u>5327790</u>	250	06/19/1992	REACTION SENSING TORQUE ACTUATOR	SALISBURY, J. KENNETH
<u>08130639</u>	<u>5625576</u>	150	10/01/1993	FORCE REFLECTING HAPTIC INTERFACE	SALISBURY, J. KENNETH
<u>08166594</u>	Not Issued	161	12/13/1993	SYSTEM AND METHOD FOR MEASURING JOINT MOVEMENT	SALISBURY, J. KENNETH
<u>08627432</u>	<u>6111577</u>	150	04/04/1996	METHOD AND APPARATUS FOR DETERMINING FORCES TO BE APPLIED TO A USER THROUGH A HAPTIC INTERFACE	SALISBURY, J. KENNETH
<u>08691247</u>	<u>6084587</u>	150	08/02/1996	METHOD AND APPARATUS FOR GENERATING AND INTERFACING	SALISBURY, J. KENNETH

				WITH A HAPTIC VIRTUAL REALITY ENVIRONMENT	
<u>08771484</u>	<u>5898599</u>	150	12/23/1996	FORCE REFLECTING HAPTIC INTERFACE	SALISBURY, J. KENNETH
<u>08857655</u>	<u>5797900</u>	150	05/16/1997	WRIST MECHANISM FOR SURGICAL INSTRUMENT FOR PERFORMING MINIMALLY INVASIVE SURGERY WITH ENHANCED DEXTERITY AND SENSITIVITY	SALISBURY, J. KENNETH
<u>08857776</u>	<u>5792135</u>	150	05/16/1997	ARTICULATED SURGICAL INSTRUMENT FOR PERFORMING MINIMALLY INVASIVE SURGERY WITH ENHANCED DEXTERITY AND SENSITIVITY	SALISBURY, J. KENNETH
<u>08858048</u>	<u>5807377</u>	150	05/16/1997	FORCE-REFLECTING SURGICAL INSTRUMENT AND POSITIONING MECHANISM FOR PERFORMING MINIMALLY INVASIVE SURGERY WITH ENHANCED DEXTERITY AND SENSITIVITY	SALISBURY, J. KENNETH
<u>09030661</u>	<u>5976122</u>	150	02/25/1998	ARTICULATED SURGICAL INSTRUMENT FOR PERFORMING MINIMALLY INVASIVE SURGERY WITH ENHANCED DEXTERITY AND SENSITIVITY	SALISBURY, J. KENNETH
<u>09324137</u>	<u>6369834</u>	150	06/02/1999	METHOD AND APPARATUS FOR DETERMINING FORCES TO BE APPLIED TO A USER THROUGH A HAPTIC INTERFACE	SALISBURY, J. KENNETH
<u>09340946</u>	<u>6371952</u>	150	06/28/1999	ARTICULATED SURGICAL INSTRUMENT FOR PERFORMING MINIMALLY INVASIVE SURGERY WITH ENHANCED DEXTERITY AND SENSITIVITY	SALISBURY, J. KENNETH
<u>09398507</u>	<u>6714839</u>	150	09/17/1999	MASTER HAVING REDUNDANT DEGREES OF FREEDOM	SALISBURY, J. KENNETH
<u>09398960</u>	<u>6459926</u>	150	09/17/1999	REPOSITIONING AND REORIENTATION OF MASTER/SLAVE RELATIONSHIP IN MINIMALLY INVASIVE TELESURGERY	SALISBURY, J. KENNETH
<u>09399457</u>	Not Issued	168	09/17/1999	COOPERATIVE MINIMALLY INVASIVE TELESURGICAL SYSTEM	SALISBURY, J. KENNETH
<u>09433120</u>	<u>6659939</u>	150	11/03/1999	COOPERATIVE MINIMALLY INVASIVE TELESURGICAL SYSTEM	SALISBURY, J. KENNETH
<u>09464455</u>	<u>6522906</u>	150	12/14/1999	DEVICES AND METHODS FOR	SALISBURY, J.

				PRESENTING AND REGULATING AUXILIARY INFORMATION ON AN IMAGE DISPLAY OF A TELESURGICAL SYSTEM TO ASSIST AN OPERATOR IN PERFORMING A SURGICAL PROCEDURE	KENNETH
<u>11243730</u>	Not Issued	20	10/04/2005	Articulated surgical instrument for performing minimally invasive surgery with enhanced dexterity and sensitivity	SALISBURY, J. KENNETH
<u>60059395</u>	Not Issued	159	09/19/1997	FORCE REFLECTING SURGICAL INSTRUMENT FOR PERFORMING MINIMALLY INVASIVE SURGERY	SALISBURY, J. KENNETH
<u>60116842</u>	Not Issued	159	01/22/1999	REPOSITIONING AND REORIENTATION OF MASTER/SLAVE RELATIONSHIP IN MINIMALLY INVASIVE TELESURGERY	SALISBURY, J. KENNETH
<u>60017981</u>	Not Issued	159	05/20/1996	TELEOPERATOR SLAVE FOR ENDOSCOPIC SURGERY	SALISBURY, J.K.

Inventor Search Completed: No Records to Display.

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**Inventor Name Search Result**

Your Search was:

Last Name = COSTA

First Name = IVAN

Application#	Patent#	Status	Date Filed	Title	Inventor Name
10016661	Not Issued	71	10/29/2001	Long elements method for simulation of deformable objects	COSTA, IVAN F.

Inventor Search Completed: No Records to Display.

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**PALM INTRANET**Day : Monday
Date: 7/17/2006
Time: 12:28:18**Inventor Name Search Result**

Your Search was:

Last Name = BALANIUK

First Name = REMIS

Application#	Patent#	Status	Date Filed	Title	Inventor Name
10016661	Not Issued	71	10/29/2001	Long elements method for simulation of deformable objects	BALANIUK, REMIS

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